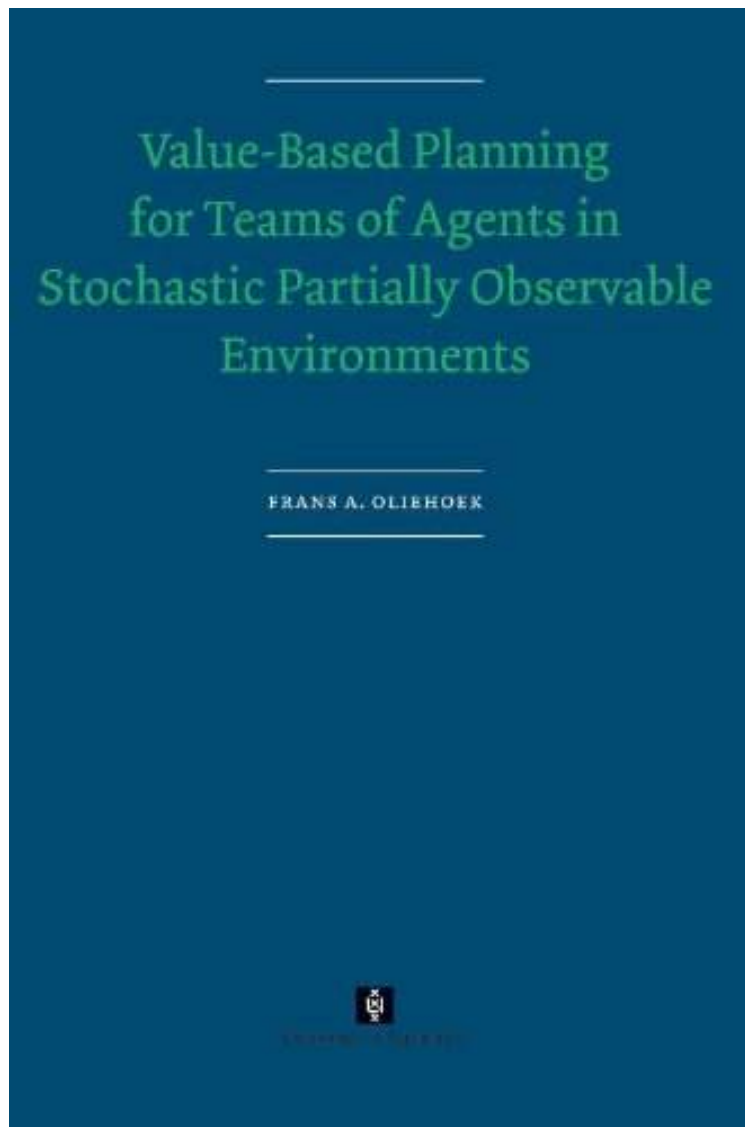


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## Value-Based Planning for Teams of Agents in Stochastic Partially Observable Environments (AUP Dissertation Series)

*By Frans Adriaan Oliehoek*

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Value-Based Planning for Teams of Agents in Stochastic Partially Observable Environments (AUP Dissertation Series):

A key requirement of decision support systems is the ability to reason about uncertainty. This is a complex problem especially when multiple decision makers are involved. For instance, consider a team of fire fighting agents whose goal is to extinguish a large fire in a residential area using only local observations. In this case, the environment is stochastic because the agents may be uncertain with respect to 1) the effect of their actions, 2) the true state of the environment. Frans Oliehoek, 1981, studeerde Informatica aan de Universiteit van Amsterdam. In 2005 behaalde hij zijn M.Sc. in de Kunstmatige Intelligentie en begon zijn Ph.D. binnen de Intelligente Autonome Systemen groep. Dit proefschrift bundelt een selectie van zijn onderzoek.

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